



Development of a Three Dimensional Fluorescence Tracking Microscope for the Motional Analysis and Behavioral Stimulation of *C. elegans*

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ABSTRACT

- Behavioral models of *C. elegans* in 2D impose constraints on the worm's motion, restricting the set of possible natural behavioral states it can occupy.
- Addressing limitations encountered by previous efforts in 3D imaging, we designed and built a microscope capable of tracking the motion of freely moving *C. elegans* via a set of motorized stages.
- The variation of gelatin concentration and the utilization of temporally controlled ultraviolet stimulation were also incorporated into the system. The addition of a refractive index mismatch correction chamber and fluorescence detection enable novel opportunities for observation and categorization of motion.
- A model of motion based on sinusoidal wave propagation was applied to *C. elegans*' forward locomotion, categorizing a set of three 3D motional states: sinusoidal in the worm's ventrodorsal plane, sinusoidal in their lateral plane, and a third state that is helical in shape.

INTRODUCTION

- The study of *C. elegans* has traditionally utilized 2 dimensional surfaces like agar to make inferences about their behavior; however, the natural worm environment is three dimensional, begging the questions:
 - how does this restriction to two dimensions affect the fundamental motion of *C. elegans*? Is this restriction justified?
 - How does motion change when the worm is given different stimuli?



Figure 1. Sample data from a previous paper by Kwon, et al.

OBJECTIVES

- Observe behavior of *C. elegans* in 3 dimensions in high definition
- Discover new patterns in motion of *C. elegans*
- Study the response of the worm's behavior to changes in firmness of surrounding environment (gelatin concentration) and blue-violet (405nm) light intensity

OUR MODEL

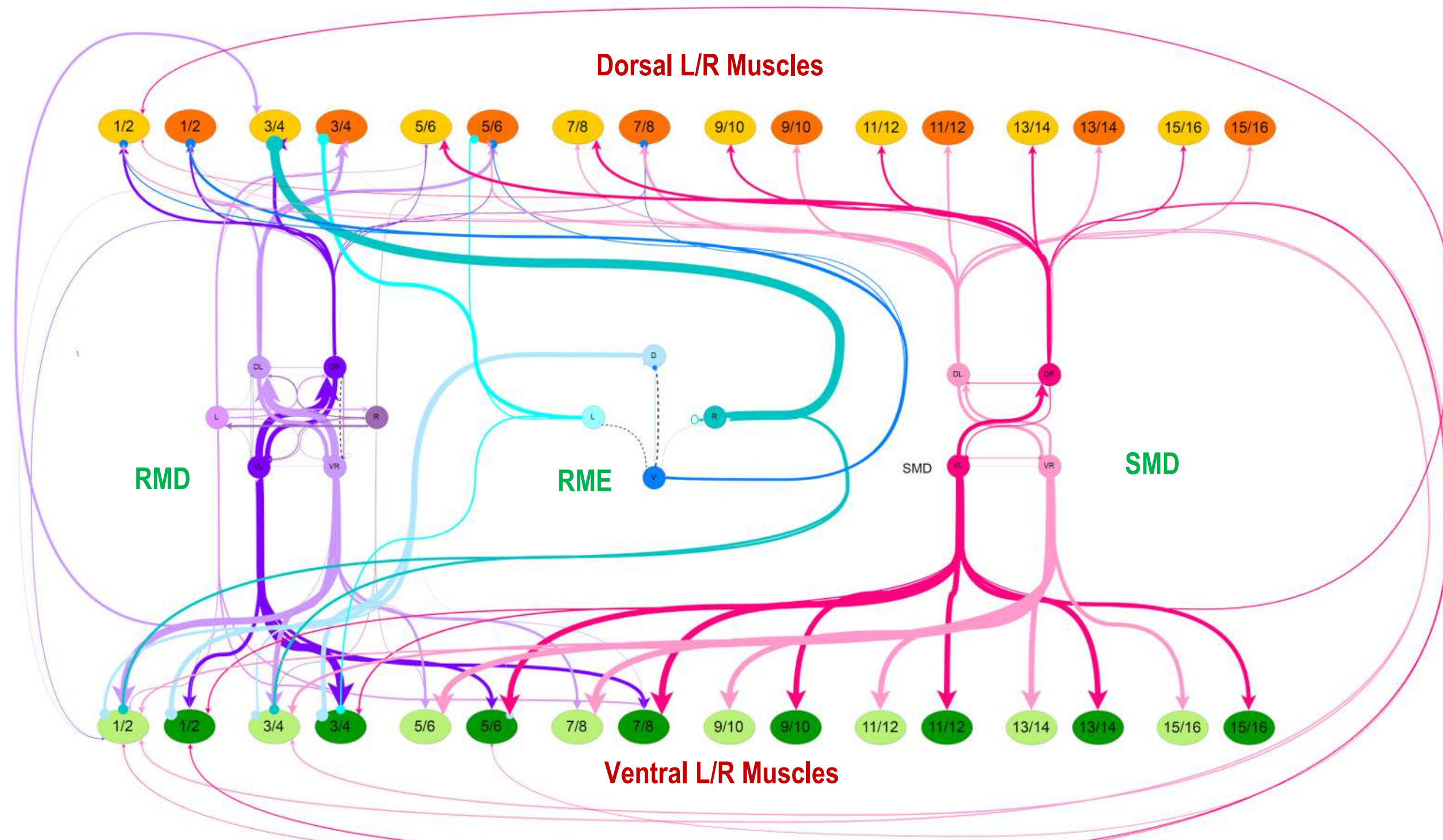


Figure 2. Rhythmic oscillations in central pattern generating (CPG) neurons RMD and SMD control head and body motion respectively

$$S_L(t) = A_1 \sin(\omega_1 t + \phi_1) \quad S_R(t) = A_2 \sin(\omega_2 t + \phi_2)$$

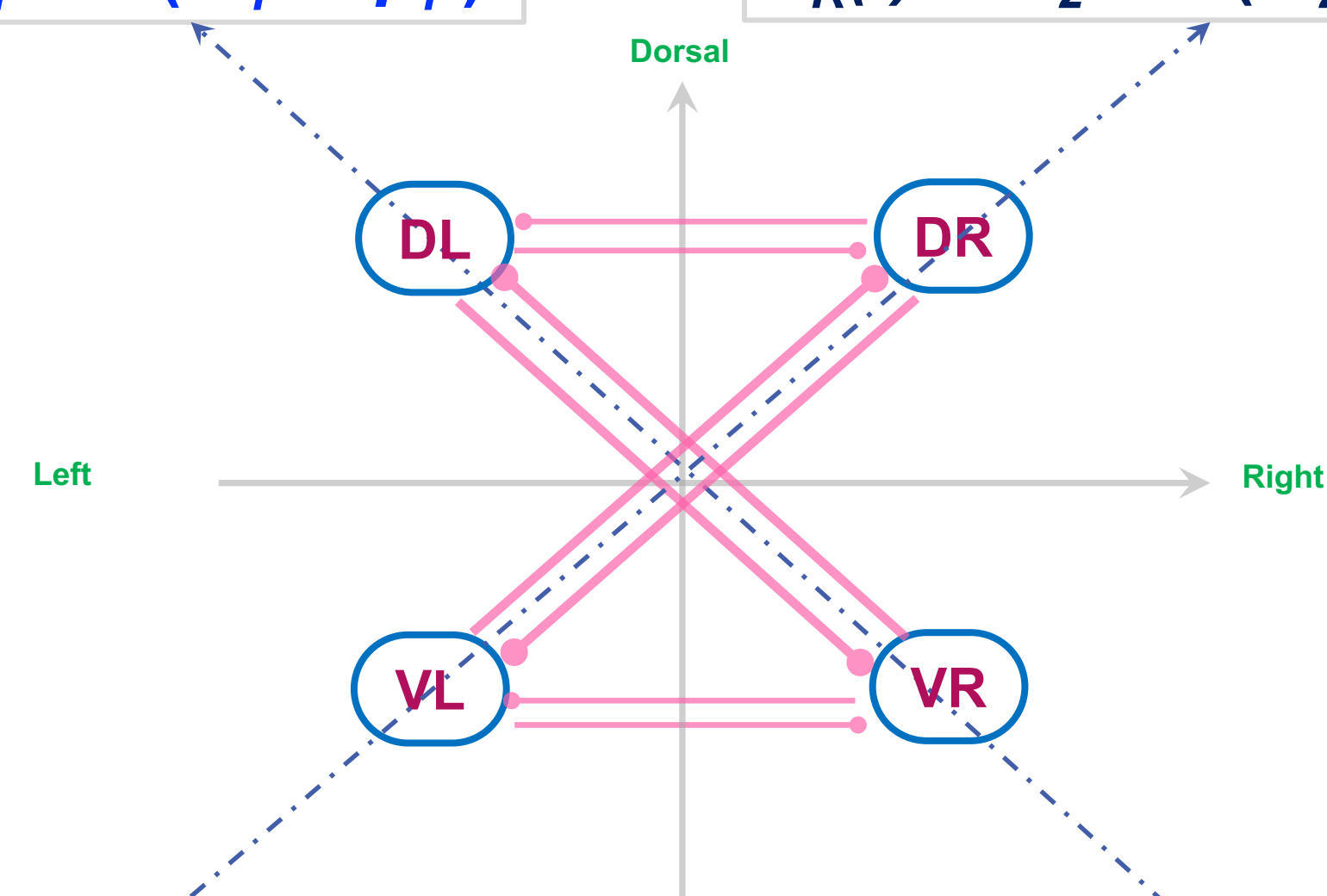


Figure 3. Oscillation in diagonal pairs (DL/VR, DR/VL) of CPG neurons drive sinusoidal locomotion. Phase difference of superimposed waves determines motional state: LR plane, DV plane, or 3D helical motion

HARDWARE

Materials:

- 3 cm cube filled with gelatin containing *C. elegans*
- 3 Basler NIR cameras with 5X objectives, 100mm tube lenses and adjustable irises
- Top camera has a 405nm violet laser to provide photon stimulation
- 3 Zaber linear stages at 90° to each other to keep *C. elegans* at center of field of view in each camera
- Outer water tank fixes distortion from air-gelatin refractive index disparity
- 472nm laser to fluorescently image ventral nerve cord in ST2 worms

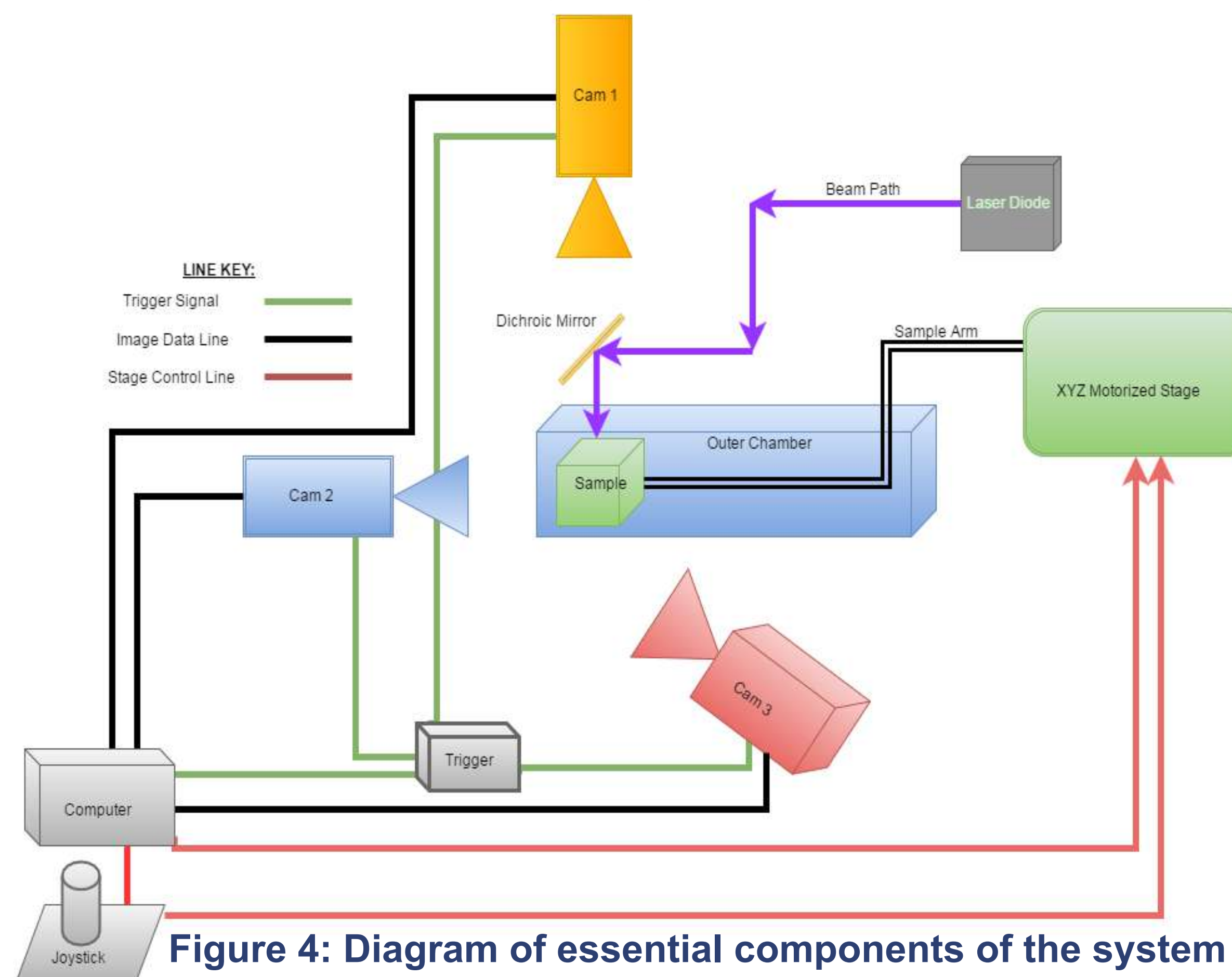


Figure 4: Diagram of essential components of the system

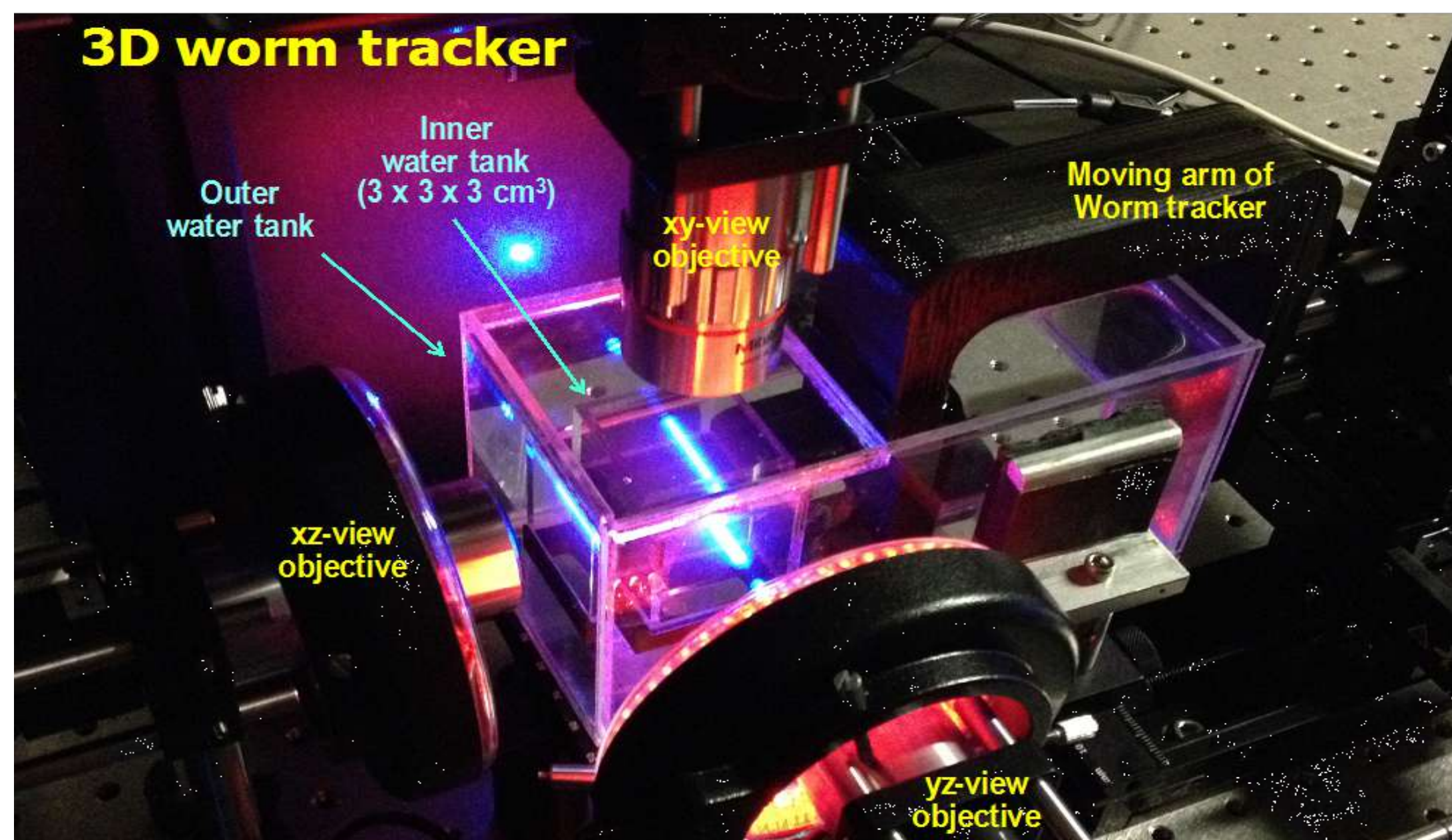


Figure 5: Image of the 3D worm tracking system

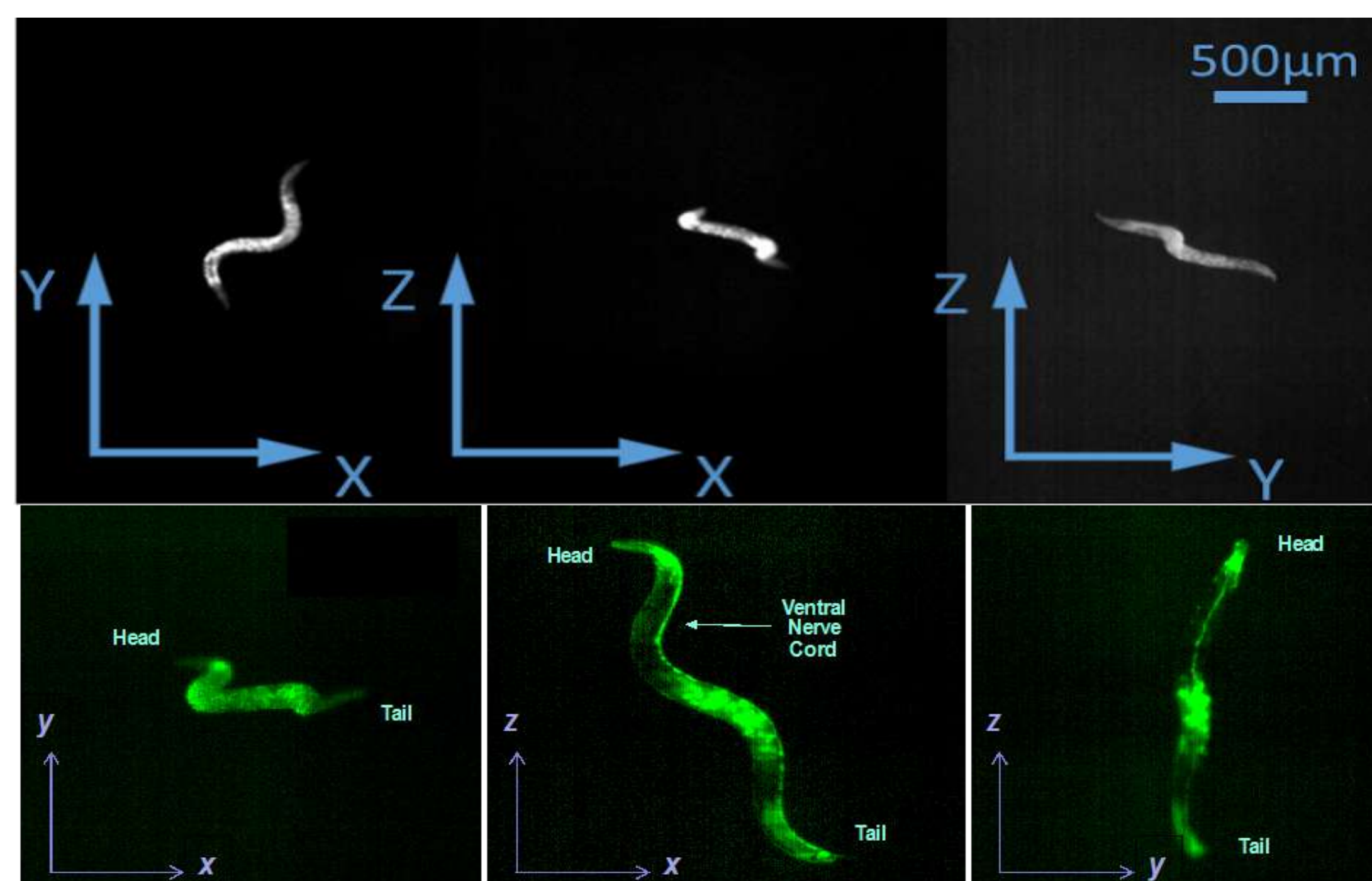


Figure 6: Images taken using the system using red light (top) and GFP fluorescence (bottom)

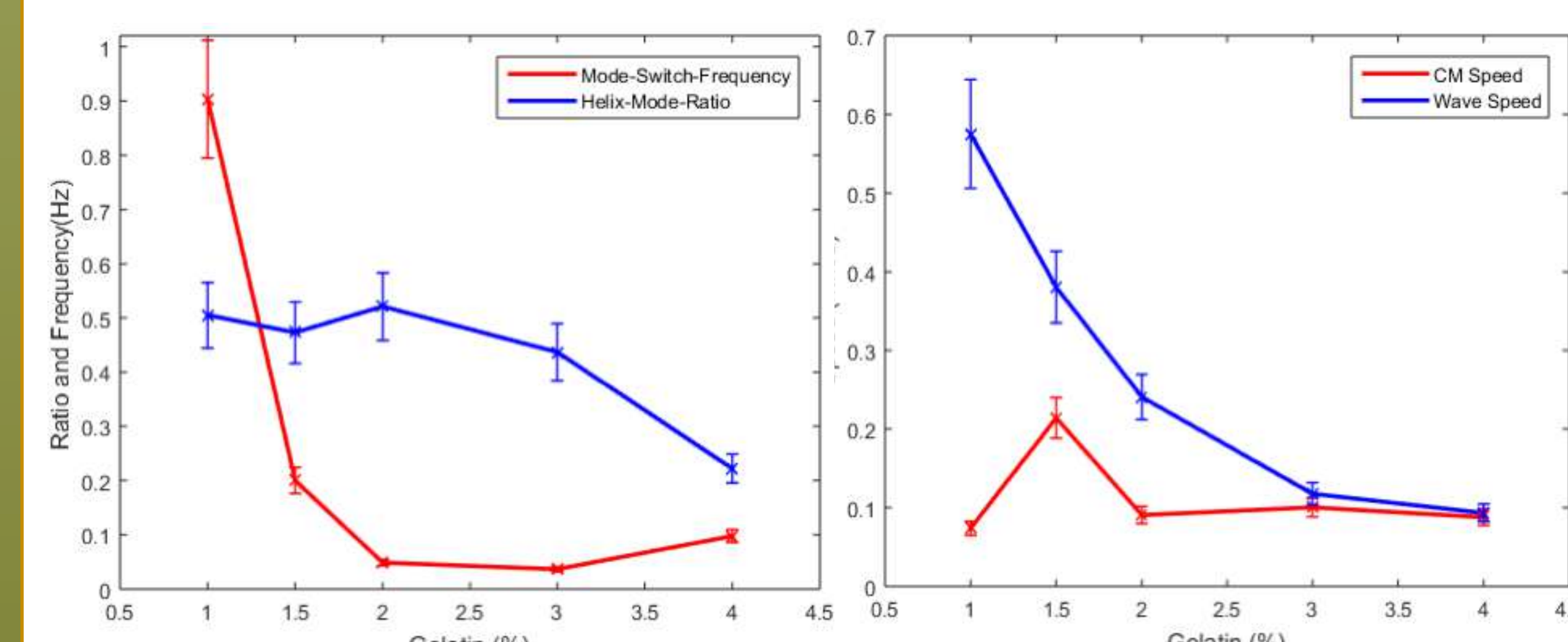
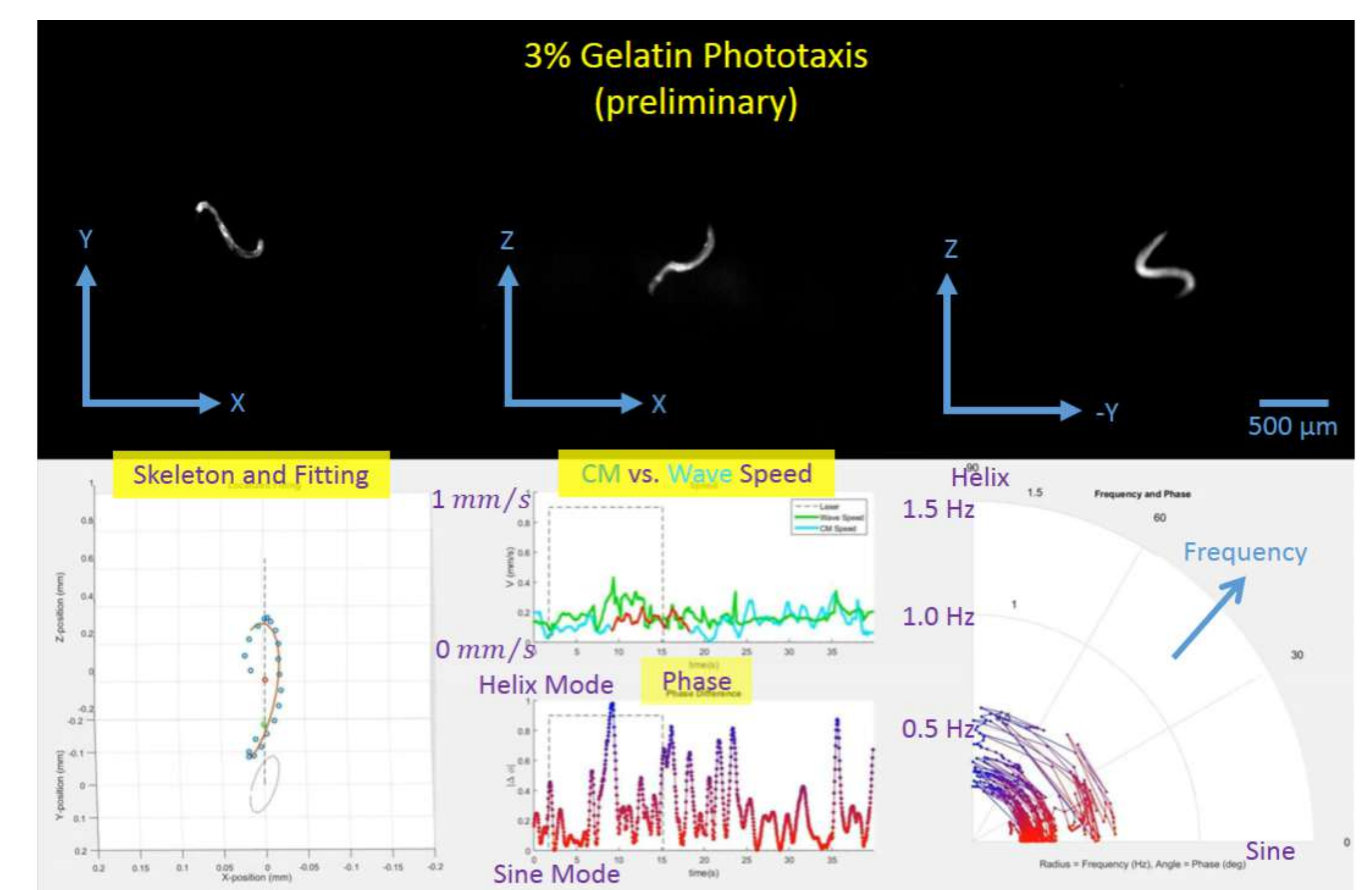
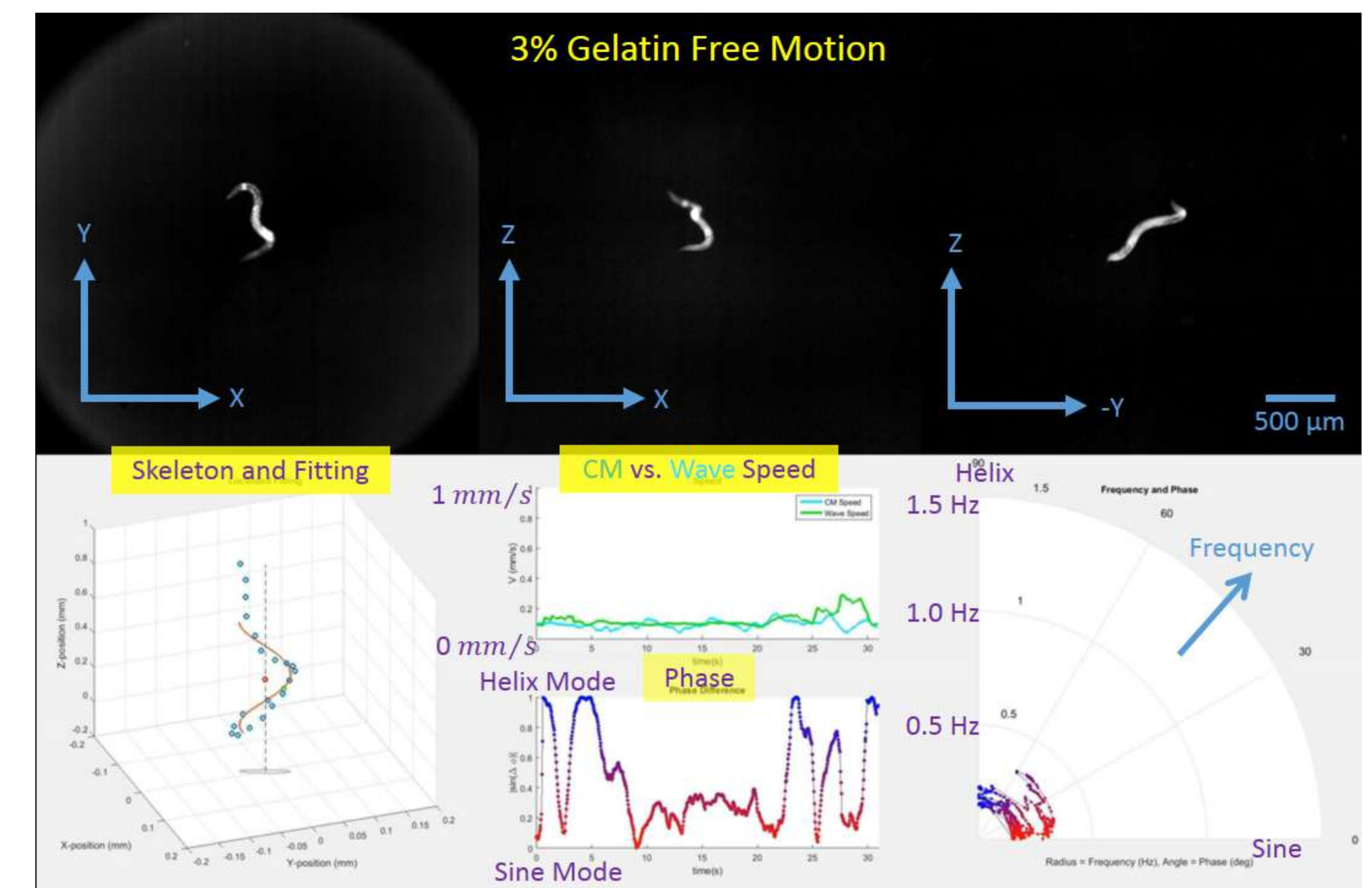
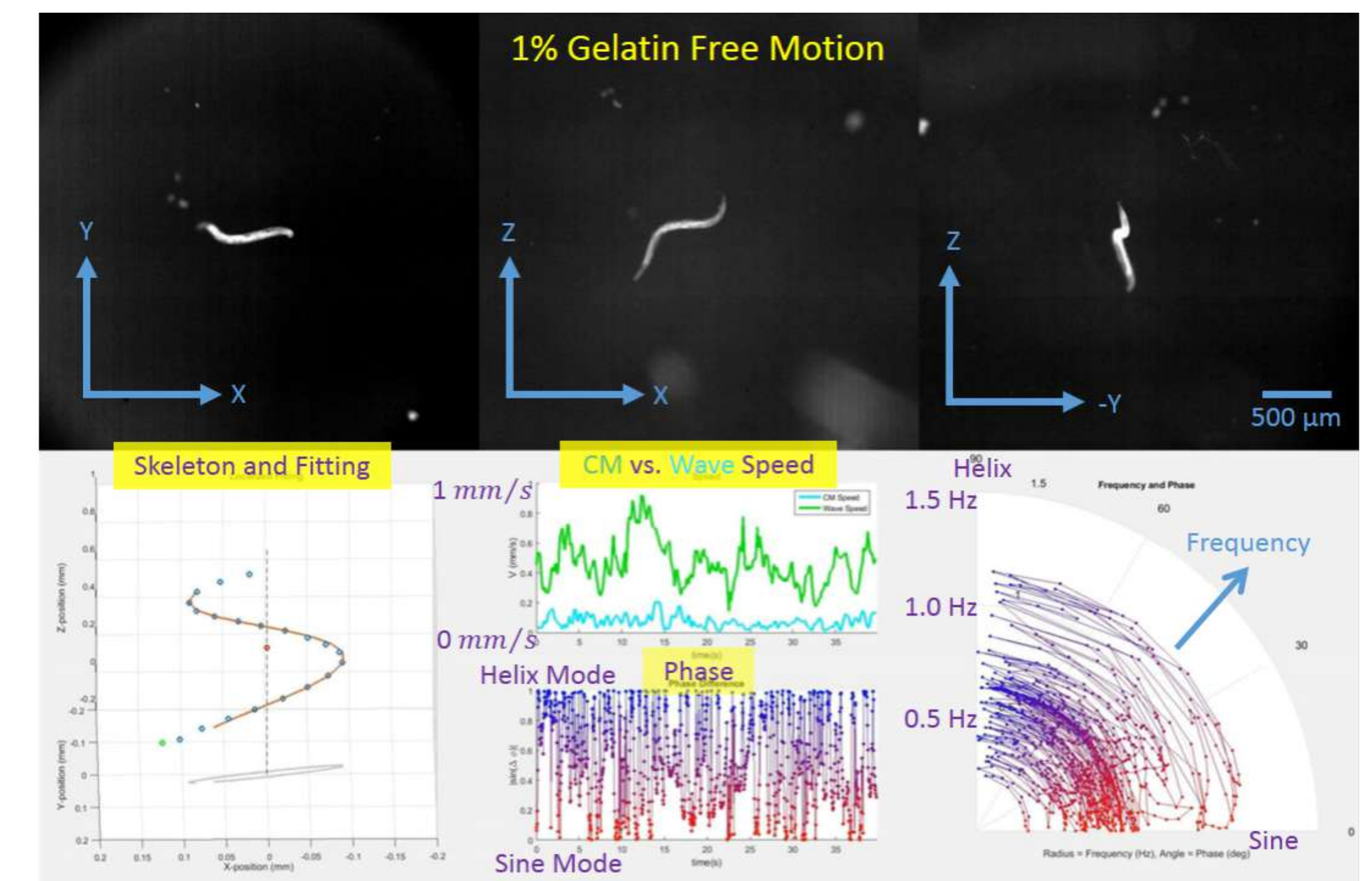
CONCLUSIONS

- Planar Sine Mode (PSM) of motion and Helix Mode (HM) of motion
- Transitional states between PSM and HM
- Dependence of PSM, HM and their transitions on gelatin percent
- Increased complexity in behavior in response to laser stimulation

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RESULTS



Figures 7-10: Results of analysis in terms of 'wave representation' of worm motion - speed and frequency as a function of gelatin concentration

REFERENCES

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